### PocketLab on Windows 10: Beta version of the PocketLab Web App available now

The PocketLab Web App is now available on Windows 10 devices as a beta version. The PocketLab Web App connects to PocketLab Voyager and Weather through a Chrome web browser. To connect your PocketLab Voyager or Weather follow the steps below.

# Instructions for Connecting a PocketLab to the PocketLab Web App

- 1. Turn your device Bluetooth on.
- 2. Open a Chrome internet browser (other internet browsers do not work at this time).
- 3. Go to thepocketlab.com/app.
- 4. Click the button that says "Connect to PocketLab."
- 5. A pop-up connection window should appear.
- 6. Turn on your PocketLab Voyager or Weather.
- 7. Click on your PocketLab name in the connection, then click "Connect."

## **Required Windows 10 Specs**

- Updated Windows 10 operating system
- Bluetooth 4.0
- Updated Chrome internet browser.

-For details on how to update your Chrome browser, follow this link:

## **Quick Start Connection Video for Windows 10 (beta)**

https://youtu.be/IKVZMszjFQ0

#### **Beta Version**

Support for the PocketLab Web App on Windows 10 is very new. You may encounter issues or bugs. There are many different Windows 10 devices and we can't test them all. Your feedback and testing will be helpful to bringing full support to Windows 10. If you find issues while using the PocketLab Web App on Windows 10 please let us know by emailing <a href="mailto:contact@thepocketlab.com">contact@thepocketlab.com</a> with the subject "Windows 10 Beta Feedback".

#### Known Bug on PocketLab Web App for Windows 10

There is a known bug on the Windows 10 version of the PocketLab Web App that we are currently working on fixing. Graphs that use the BME sensor component are not displaying properly. The graphs affected are Internal Temperature, Barometric Pressure, Altitude, Humidity, Dew Point, and Heat Index.

Graphs that use all other sensor components are working correctly. Those graphs are Acceleration, Acceleration Scalar, Angular Velocity, Magnetic Field, Magnetic Field Magnitude, Rangefinder Position, Rangefinder Velocity, Light Intensity, and Temperature Probe.